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A Purchasing Inventory Model for Breakable items with Permissible Delay in Payments and Price Discount

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Abstract. In this paper, a purchasing inventory model with an aim to minimize the total inventory cost and to find the optimal time interval is discussed. Here the retailers are given trade credit offer. In this model, supplier provides replacement, or price discount for damageable items. Shortages are allowed and backlogged. The results are illustrated with numerical example.

Keywords: inventory control, permissible delay in payments, deteriorating items, trade credit period, price discount.

AMS Mathematics Subject Classification (2010): 90B05

1. Introduction

An important assumption in inventory models found in the existing literature is that the life time of an item is infinite while it is in storage. But the effect of deterioration plays an important role in the storage of some commonly used decaying items like, breakable items (glass, china clay, ceramic goods...etc). Due to the deterioration in stored products some of these items loses their quality and cannot complete the customer's need for ideal product. Deterioration in these items may be constant, continuous, time dependent or stock dependent. The economic order quantity model is based on the assumption that the retailer paid for the items immediately after the items are received. However, in practice, the supplier may provide the retailer many incentives such as a cash discount to motivate faster payment and stimulate sales, or a permissible delay in payment to attract new customer and increase the sales. Hence trade credit can play a major role in inventory control for both the supplier as well as retailer. [1] Goyal first developed the EOQ model under the conditions of permissible delay in payments, [2] Ray (2014) considered a nonlinear EOQ model with effect of trade credit. In [3] Sajadifar, Ahmadavaji developed an inventory model with demand dependent replenishment rate for damageable items and shortages. In [4] Mukesh Kumar et al developed a deterministic inventory model for deteriorating items with price dependent demand and time varying holding cost under trade credit. In [6] Tangam A considered Retailers inventory system in a two level trade credit financing with selling price discount and partial order cancellations. [5] Palanivel M et al consider an EOQ model for non-instantaneous deteriorating items with power

demand time dependent holding cost, partial backlogging and permissible delay in payments. Recently many authors developed an EOQ model for deteriorating items with quadratic demand rate under permissible delay in payments.

In this modelcustomer may pay cashwhen the supplier offered trade credit to the retailer. The shortages are allowed when unsatisfied demand will be backlogged in each cycle. The demand rate is time dependent, and the suitable numerical example is given to illustrate the model.

2. Notations and assumptions

2.1. Notations

The following notations have been used in developing the model.

- A The ordering cost per order.
- P- The purchasing rate per unit time per year.
- Q- The initial inventory level.

D(t)-The demand rate at any time t ≥ 0 , D(t)=a+bt,a,b>0 where a, b are positive constants.

- T- The length of replenishment cycle.
- r- The price discount.
- h- The holding cost per unit per unit time.
- θ The rate of damageable items.
- I_e- Interest which can be earned per year.
- I_p- Interest payable per year.
- \dot{C}_1 The shortage cost for backlogged items per unit per year.
- t₁- The time at which the inventory level reaches zero.
- t_r- The replacement time and trade credit period.

m_o-The mark up of selling price for damaged items.

B(Q)-The number of damaged units per unit of time at time t and is a function of current inventory level Q

TC - The minimum total cost per unit time.

2.2. Assumptions

The following assumptions are made in developing the model

- 1. The supplier offers price discount to his retailer at $t_1 < t_r$.
- 2. The breakable items are replaced when end of the trade credit period.
- 3. The time horizon is infinite.
- 4. The lead time is zero.
- 5. Shortages are allowed and backlogged.
- 6. Selling price for damaged items S_d is a multiple of purchasing cost. $S_d{=}m_0 \ast P$ $0{\leq}\,m_0{\leq}1.$

3. Mathematical formulation

Based upon the above notations and assumptions are to be defined as follows.

Case I $t_1 > t_r$ The retailer replaced breakable items at end of the permissible delay period.

Case II $t_1 < t_r$

The retailer adopts each discount to settle the accounts and the payments in time t_r

Case III $t_1 = t_r$

The retailer replacesbreakable items at the end of the permissible period, at the time of inventory level is zero.

3.1. Case I $t_1 > t_r$

In this section, the detailed mathematical formulation for the inventory problem is given. The inventory level is dropping to zero because of demand and damageable items during the interval $[0, t_1]$. The period $[0, t_r]$ is delay in payments and t_r is the replacement time for damageable items. Finally the shortage occurs due to demand and backlogging during the time interval $[t_1, T]$, based on the above description, the inventory level at time t, I(t) will be described by the following differential equation.



$$\begin{aligned} \frac{dI(t)}{dt} + \theta I(t) &= -D(t) & 0 < t < t_r \end{aligned} \tag{1}$$
With the condition t=0 and I(t)=Q the solution of (1) is
$$I(t) &= Q(1 - \theta t) - at & 0 < t < t_r \end{aligned} \tag{2}$$
During the time interval $[t_r, t_1]$, the differential equation representing the inventory status is given by $\frac{dI(t)}{dt} + \theta I(t) &= -D(t) & t_r < t < t_1 \end{aligned}$
(3)
With the boundary condition $I(t_r) = Q(1 - \theta t) - at + Q\theta$ the solution of (2) is
$$I(t) = \left[Q(1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta}\right](\theta t_r - \theta t + 1) - \frac{bt_r}{\theta} + a(t_r - t)t_r < t < t_1 \end{aligned}$$
(4)
With the condition t=t_1 and $I(t_1)=0$ the solution
$$t_1 = \frac{\left[Q(1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta}\right](\theta t_r + 1) - \left(\frac{b}{\theta} - a\right)t_r}{\left[Q(1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta}\right]} \end{aligned}$$
(5)
During the third interval $[t_1, T]$, shortages occurred and the demand is backlogged, when

During the third interval $[t_1, T]$, shortages occurred and the demand is backlogged, when t=T. The inventory level at time t is governed by the following differential equation $\frac{dI(t)}{dt} = -D(t)t_1 < t < T$ (6)
With the boundary conditions are $I(t_1) = 0$, $I(T) = -(1 - \theta)[a + b(T - t_1)]$

$$I(t) = \left[a(T-t) + \frac{b}{2}(T^2 - t^2) - (1-\theta)[a+b(T-t_1)]t_1 < t < T\right]$$

The ordering cost is OC=A The purchasing cost is PC=P * Q + $(1 + \theta)[a + b(T - t_1)]$ The total inventory holding cost for the cycle $[0,t_1]$ is $HC = h \int_0^{t_1} I(t) dt$

$$HC = h \left\{ \int_{0}^{t_{r}} I(t)dt + \int_{t_{r}}^{t_{1}} I(t)dt \right\}$$
$$HC = h \left\{ Q \left(t_{r} - \frac{\theta t_{r}^{2}}{2} \right) - \frac{a t_{r}^{2}}{2} + \left(Q (1 - \theta t_{r} + \theta) - a t_{r} + \frac{b t_{r}}{\theta} \right) \left(\frac{\theta}{2} (t_{1} - t_{r})^{2} - \theta t_{r} (t_{r} - 2) + 2t_{1} \right) - (t_{1} - t_{r}) \left(\frac{b t_{r}}{\theta} + \frac{a}{2} (t_{1} - t_{r}) \right) \right\}$$
(7)

The total shortage cost SC during the period $[t_1, T]$ is given by $SC = C_1 \int_{t_1}^{T} I(t) dt$ $SC = C_1 \left[\frac{b}{6} (2T^3 - 3T^2t_1 + t_1^3) + \left(\frac{a}{2} - b(1 - \theta) \right) (T - t_1)^2 - a(1 - \theta)(T - t_1) \right]$ (8) The interest earned per unit time in $[0, t_r]$ is $IE = SI_e \int_0^{t_r} D(t) dt$ $IE = SI_e \left[at_r + \frac{bt_r^2}{2} \right]$ (9)

 $IE = SI_{e} \left[at_{r} + \frac{bt_{r}^{2}}{2} \right]$ (9) The interest payable per cycle per unit time for the inventory not being after due date say $t_{r} isIP = PI_{p} \int_{t_{r}}^{t_{1}} I(t) dt$ $IP = PI_{p} \left[\left(O(1 - \theta t_{r} + \theta) - at_{r} + \frac{bt_{r}}{2} \right) \left(\frac{\theta}{2} (t_{1} - t_{r})^{2} - \theta t_{r} (t_{r} - 2) + 2t_{1} \right) - 0 \right]$

$$P = PI_p \left[\left(Q(1 - \theta t_r + \theta) - a t_r + \frac{b t_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{b t_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right]$$
(10)

So, the total variable cost per unit time is
$$TC = \frac{1}{T} [OC + PC + HC + SC + IP - IE] TC = \frac{1}{T} \left\{ A + P * Q + (1 - \theta)[a + b(T - t_1)] + h \left\{ Q \left(t_r - \frac{\theta t_r^2}{2} \right) - \frac{a t_r^2}{2} + \left(Q (1 - \theta t_r + \theta) - a t_r + \frac{b t_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2 t_1 \right) - (t_1 - t_r) \left(\frac{b t_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right\} + C_1 \left[\frac{b}{6} (2T^3 - 3T^2 t_1 + t_1^3) + \left(\frac{a}{2} - b(1 - \theta) \right) (T - t_1)^2 - a(1 - \theta)(T - t_1) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - a t_r + \frac{b t_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2 t_1 \right) - (t_1 - t_r) \left(\frac{b t_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] - SI_e \left[a t_r + \frac{b t_r^2}{2} \right] \right\}$$
(11)
For minimizing the total relevant cost per unit time, the approximate optimal values of T

For minimizing the total relevant cost per unit time, the approximate optimal values of T can be obtained by solving the following equation $\frac{dTC}{dT} = 0$ $\frac{dTC}{dT} = -\frac{1}{T^2} \left\{ A + P * Q + (1 - \theta)(a - bt_1) + h \left[Q \left(t_r - \frac{\theta t_r^2}{2} \right) - \frac{at_r^2}{2} + \left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r^2}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] - SI_e \left[at_r + \frac{bt_r^2}{2} \right] + C_1 \left[\frac{b}{6} t_1^3 + \left(\frac{a}{2} - b(1 - \theta) \right) t_1^2 + a(1 - \theta) t_1 \right] \right\} + C_1 \left[\frac{a}{2} - b \left(1 - \theta - \frac{t_1}{2} \right) \right] + C_1 2bT = 0$ This also satisfies the conditions $\frac{d^2TC}{dT^2} = \frac{2}{T^3} \left\{ A + P * Q + (1 - \theta)(a - bt_1) + h \left[Q \left(t_r - \frac{\theta t_r^2}{2} \right) - \frac{at_r^2}{2} + \left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - (t_1 - t_r) \left(\frac{bt_r}{\theta} + \frac{a}{2} (t_1 - t_r) \right) \right] + PI_p \left[\left(Q (1 - \theta t_r + \theta) - at_r + \frac{bt_r}{\theta} \right) \left(\frac{\theta}{2} (t_1 - t_r)^2 - \theta t_r (t_r - 2) + 2t_1 \right) - \left(t_r - 2 \right) + 2$

$$t_{r})\left(\frac{bt_{r}}{\theta} + \frac{a}{2}(t_{1} - t_{r})\right) - SI_{e}\left[at_{r} + \frac{bt_{r}^{2}}{2}\right] + C_{1}\left[\frac{b}{6}t_{1}^{3} + \left(\frac{a}{2} - b(1 - \theta)\right)t_{1}^{2} + a(1 - \theta)t_{1}\right] + C_{1}2b > 0$$
(13)

3.2. Case II

3.2. Case II $t_1 < t_r$ In this case, the inventory level reduces due to demand rate as well as damageable/breakable items rate during the inventory [0, t₁]. At the period, price discount is allowed for damageable/breakable items. The time t_r is permissible delay in payments for the retailer. Finally shortages occur due to demand and backlogging during the time inventory [t₁,T]. The differential equation representing the inventory status is



 $\frac{\mathrm{dI}(t)}{\mathrm{dt}} + \theta \mathrm{I}(t) = -\mathrm{D}(t) \qquad 0 < t < t_1$ (14)With the condition t=0 and I (t) =Q the solution of (1) is $I(t) = Q(1 - \theta t) - at$ The boundary conditions are as follows $I(t_1) = 0$ $t_1 = \frac{Q}{\theta Q + a}$ (15)

During the interval [t₁, T] the backlogged at time I(t) is governed by the following differential equation From Equation (6)

$$I(t) = \left[a(t_1 - t) + \frac{b}{2}(t_1^2 - t^2) \right]$$
The ordering cost is OC=A
(16)

The purchasing cost is PC=P*Q

The holding cost for the period $[0,t_1]$ is $HC = h \int_0^{t_1} I(t) dt$

$$HC = h \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right]$$
(17)

The shortage cost for the period $[t_1,T]$ is $SC = C_1 \int_{t_1}^{t} I(t) dt$

$$SC = C_1 \left[\frac{b}{6} \left(3t_1^2 T - T^3 - 2t_1^3 \right) - \frac{a}{2} (T - t_1)^2 \right]$$
Breaking cost: Total number of damageable/breakable units is
(18)

$$\theta(Q_0) = \int_0^{t_1} B(Q_0) dt = a_1(Q_0)^r t_1$$

Where $B(Q_0)$ is breaking rate when inventory level is Q and it can be substituted as $followsB(Q_0) = a_1(Q_0)^r$ 0 < r < 1.

As mentioned, selling price for each damaged item is $S_b=m_0 *P$, $0 < m_0 < 1$ which is a multiple of last purchasing cost. So total selling price for damageable item is

$$= \theta(Q_0)^r * m_0 * P$$

= $a_1(Q_0)^r t_1 * m_0 * P$ (19)

In this Case, annual interest earned is
$$IE = SI_e \left\{ \int_0^{t_1} I(t)dt + (t_r - t_1) \int_{t_1}^{t_r} I(t)dt \right\}$$

 $IE = SI_e \left\{ \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right] + \beta (t_r - t_1) \left[\frac{b}{6} \left(3t_1^2 t_r - t_r^3 - 2t_1^3 \right) - \frac{a}{2} (t_r - t_1)^2 \right] \right\}$
(20)

From the above arguments, the annual total relevant cost incurred at the retailer is $TC = \frac{1}{10} [OC + BC + BC + SC - IE - Cost of D items]$

$$TC = \frac{1}{T} \left[0C + PC + HC + SC - IE - Cost of D. items \right]$$

$$TC = \frac{1}{T} \left\{ A + P * Q + h \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right] + C_1 \left[\frac{b}{6} \left(3t_1^2 T - T^3 - 2t_1^3 \right) - \frac{\theta t_1^2}{2} \right] - SI_e \left\{ \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right] + (t_r - t_1) \left[\frac{b}{6} \left(3t_1^2 t_r - t_r^3 - 2t_1^3 \right) - \frac{\theta t_1^2}{2} \right] - \frac{\theta t_1^2}{2} \right] + (t_r - t_1) \left[\frac{b}{6} \left(3t_1^2 t_r - t_r^3 - 2t_1^3 \right) - \frac{\theta t_1^2}{2} \right] \right\} - a_1 (Q_0)^r t_1 * m_0 * P \right\}$$
(21)

For minimizing the total relevant cost per unit time, the approximate optimal values of T can be obtained by solving the following equation $\frac{dTC}{dT} = 0$

$$\begin{split} \frac{dTC}{dT} &= -\frac{1}{T^2} \bigg\{ A + P * Q + h \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right] \\ &- SI_e \left[\left(Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right) \\ &+ (t_r - t_1) \left(\frac{b}{6} \left(3t_1^2 t_r - t_r^3 - 2t_1^3 \right) - \frac{a}{2} (t_r - t_1)^2 \right) \right] - a_1 (Q_0)^r t_1 * m_0 \\ &+ P - C_1 \left[\frac{b t_1^3}{3} - \frac{a t_1^2}{2} \right] \bigg\} - C_1 \left[\frac{a}{2} + \frac{b T}{3} \right] = 0 \end{split}$$

This also satisfies the conditions

$$\begin{split} \frac{d^2 TC}{dT^2} &= \frac{2}{T^3} \bigg\{ A + P * Q + h \left[Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right] \\ &- SI_e \left[\left(Q \left(t_1 - \frac{\theta t_1^2}{2} \right) - \frac{\theta t_1^2}{2} \right) \\ &+ (t_r - t_1) \left(\frac{b}{6} \left(3t_1^2 t_r - t_r^3 - 2t_1^3 \right) - \frac{a}{2} (t_r - t_1)^2 \right) \right] - a_1 (Q_0)^r t_1 * m_0 \\ &+ P - C_1 \left[\frac{b t_1^3}{3} - \frac{a t_1^2}{2} \right] \bigg\} - C_1 \left[\frac{b}{3} \right] > 0 \end{split}$$

3.3. Case III

 $\mathbf{t_1} = \mathbf{t_r}$

During the positive stock period $[0,t_1]$. The inventory level decreases due to, both demand and damageable/breakable items will continue until the inventory level reaches zero at time. At the same time damageable items are replaced and permissible delay time (t_r) is also equal to t_1 . Again the inventory level decreases due to demand and damageable/breakableitems untilan inventory level become zero. Finally shortage is accumulated during (t_2, T) which is backlogged when t=T. The inventory level at the time t is governed by the following differential equations



SC = C₁
$$\left[\frac{b}{6} (2T^3 - 3T^2t_2 + t_2^3) + \left(\frac{a}{2} - b(1 - \theta) \right) (T - t_2)^2 - a(1 - \theta)(T - t_2) \right]$$

During the permissible delay period when the account is not settled the retailer sells the goods and continues to accumulate sales revenue and earn the interest with rate I_e . Therefore the interest earned in the cycle period $[0, t_2]$

$$\begin{split} IE &= SI_{e} \int_{0}^{t_{2}} I(t)dt, \qquad IE = SI_{e} \left[\int_{0}^{t_{1}} I(t)dt + \int_{t_{1}}^{t_{2}} I(t)dt \right] \\ IE &= SI_{e} \left\{ \left(Qt_{1} - \frac{t_{1}^{2}}{2}(\theta Q + a) \right) + \left(Q(1 - \theta t_{1} + \theta) - at_{1} + \frac{bt_{1}}{\theta} \right) \left(\frac{\theta(t_{2} - t_{1})^{2}}{2} + (t_{2} - t_{1}) \right) + \frac{a(t_{2} - t_{1})^{2}}{2} - \frac{b(t_{1}t_{2} - t_{1}^{2})}{\theta} \right\} \end{split}$$

From the above arguments, the annual total relevant cost incurred at the retailer is TC =

$$\frac{1}{T} [OC + PC + HC + SC - IE]TC = \frac{1}{T} \left\{ A + P * Q + (1 + \theta)[a + b(T - t_2)] + b\left[\left(Qt_1 - \frac{t_1^2}{2}(\theta Q + a) \right) + \left(Q(1 - \theta t_1 + \theta) - at_1 + \frac{bt_1}{\theta} \right) \left(\frac{\theta(t_2 - t_1)^2}{2} + (t_2 - t_1) \right) + \frac{a(t_2 - t_1)^2}{2} - \frac{b(t_1 t_2 - t_1^2)}{\theta} \right] + C_1 \left[\frac{b}{6} (2T^3 - 3T^2 t_2 + t_2^3) + \left(\frac{a}{2} - b(1 - \theta) \right) (T - t_2)^2 - a(1 - \theta)(T - t_2) \right] - SI_e \left[\left(Qt_1 - \frac{t_1^2}{2}(\theta Q + a) \right) + \left(Q(1 - \theta t_1 + \theta) - at_1 + \frac{bt_1}{\theta} \right) \left(\frac{\theta(t_2 - t_1)^2}{2} + (t_2 - t_1) \right) + \frac{a(t_2 - t_1)^2}{2} - \frac{b(t_1 t_2 - t_1^2)}{\theta} \right] \right\}$$

Our objective is to minimize the total cost per unit time TC, The necessary condition for the total cost TC to be minimize is

$$\begin{split} \frac{dTC}{dT} &= 0 \quad \frac{dTC}{dT} = -\frac{1}{T^2} \Biggl\{ A + P * Q + (1+\theta)[a - bt_2] \\ &+ h \left[\left(Qt_1 - \frac{t_1^2}{2}(\theta Q + a) \right) \right. \\ &+ \left(Q(1 - \theta t_1 + \theta) - at_1 + \frac{bt_1}{\theta} \right) \left(\frac{\theta(t_2 - t_1)^2}{2} + (t_2 - t_1) \right) \\ &+ \frac{a(t_2 - t_1)^2}{2} - \frac{b(t_1 t_2 - t_1^2)}{\theta} \Biggr] \\ &+ C_1 \left[\left(\frac{a}{2} - b(1 - \theta) \right) t_2^2 + a(1 - \theta) t_2 + \frac{b}{6} t_1^3 \right] \\ &- SI_e \left[\left(Qt_1 - \frac{t_1^2}{2}(\theta Q + a) \right) \\ &+ \left(Q(1 - \theta t_1 + \theta) - at_1 + \frac{bt_1}{\theta} \right) \left(\frac{\theta(t_2 - t_1)^2}{2} + (t_2 - t_1) \right) \\ &+ \frac{a(t_2 - t_1)^2}{2} - \frac{b(t_1 t_2 - t_1^2)}{\theta} \Biggr] \Biggr\} + C_1 \left(\frac{a}{2} - b\left(1 - \theta - \frac{t_2}{2} \right) \right) + C_1 2bT \\ &= 0 \end{split}$$

This also satisfies the conditions

 $\begin{array}{l} (d^{2} TC)/dT^{2} > 0 \ (d^{2} TC)/dT^{2} \\ &= 2/T^{3} \ \{ \blacksquare (A + P * Q + (1 + \theta)[a - bt_{2}] + @h[(Qt_{1} \\ &- \ [\ [t_{1}]\]^{2}/2(\theta Q + a)) + (Q(1 - \theta t_{1} + \theta) - at_{1} \\ &+ bt_{1}/\theta)((\theta(t_{2} - t_{1})^{2})/2 + (t_{2} - t_{1})) + (a(t_{2} - t_{1})^{2})/2 \\ &- b(t_{1} t_{2} - \ [\ [t_{1}]\]^{2}/\theta] \\ + C_{1} \ [(a/2 - b(1 - \theta))\] \ [\ [t_{2}]\]^{2} + a(1 - \theta) \ t_{2} + b/6\] \ [\ [t_{1}]\]^{3}] - SI_{e} \ [(Qt_{1} \\ &- \ [\ [t_{1}]\]^{2}/2(\theta Q + a)) + (Q(1 - \theta t_{1} + \theta) - at_{1} \\ &+ bt_{1}/\theta)((\theta(t_{2} - t_{1})^{2})/2 + (t_{2} - t_{1})) + (a(t_{2} - t_{1})^{2})/2 \\ &- b(t_{1} t_{2} - \ [\ [t_{1}]\]^{2}/2)/\theta] \) \right\} \ [\ + C \] \ 1 \ 2b > 0 \end{array}$

1. Numerical example

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S.No	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Parameters	А	a	b	I _P	Ie	h	Р	θ	Q	t _r	c ₁	S	r	m ₀
Values	150	230	0.6	0.10	0.12	0.10	15	0.15	65	0.30	4	17	0.02	0.15

For the above parametric values $t_1 = 0.27$, here $t_r=0.30 > t_1$. So using case: 2, optimal value of $T^* = 1(1.0379)$ and $TC^* = 563$ in appropriate units.

5. Conclusion

In this paper, an inventory model is developed in which the optimal cycle time is determined to minimize the total inventory cost. The shortages are allowed and are

completely backlogged. The proposed model is discussed in three cases. Finally, numerical example is given to illustrate the model.

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